



THREE-DIMENSIONAL MAGNETIC RESONANCE IMAGING

Background Of The Invention

Field of the Invention

The invention relates to magnetic resonance imaging, and more particularly to a rapid process for producing three-dimensional magnetic resonance imaging.

Description Of The Prior Art

Magnetic resonance imaging (MRI) is a non-invasive medical diagnostic imaging modality that can produce high-contrast tomographic images of the interior soft-tissue structures of the human body without the use of ionizing radiation. In many imaging applications, MRI has replaced the competing technology of X-ray computed tomography (CT) as the imaging method of choice. For an MRI examination, the subject is placed in a very strong static magnetic field, and the information necessary to create the images is generated using a series of magnetic field gradient pulses and radio-frequency (RF) pulses. The exact manner in which the gradient and RF pulses are applied is called the pulse sequence. By changing the pulse sequence, the relative appearance of different tissues and pathologies can be changed. Thus, the pulse sequence can be optimized to highlight certain pathological conditions, and even to create images of flow. There are literally an infinite number of possible pulse sequences. The potential variety of pulse sequences and the ability of different pulse sequences to produce images which highlight different types of information are major advantages of MRI compared to other techniques. Critical to the success and acceptance of MRI as a primary imaging modality has been the continued development of new pulse sequence techniques which have both improved the imaging capabilities in existing areas of clinical use and provided new clinical areas of application.

1 The importance of rapid imaging techniques is discussed in  
2 the Manual of Clinical Magnetic Resonance Imaging, (CMRI) by  
B 3 Heiken et al., Raven Press, New York, 1991. It is therein ex-  
4 plained that the impetus for the development of rapid imaging  
5 techniques has been primarily twofold: to improve the efficiency  
6 of clinical MRI and to decrease artifacts that arise from car-  
7 diac, respiratory, and other patient motion. The synopsis of the  
8 more important rapid imaging techniques discussed in CMRI, at  
B 9 pages 24 through 39, is incorporated herein by reference, as  
10 though set forth in detail. At page 31, it is noted that steady  
11 state GE images with short TRs and low flip angles provide a  
12 myelogram effect in which the spinal cord can be easily differen-  
13 tiated from surrounding CSF.

CL 15 SUMMARY OF THE INVENTION

PB 16 It has now been found that a new three-dimensional (3D) MR  
B 17 imaging pulse sequence can produce over 100 high-resolution,  
L 18 high-contrast images in as little as 6 minutes of imaging time.  
19 Without additional imaging time, this same image data can be  
20 post-processed to yield high-resolution, high-contrast images in  
21 any arbitrary orientation. Thus, this new pulse sequence tech-  
22 nique provides detailed yet comprehensive coverage. Compared to  
B 23 existing 3D MR imaging pulse sequences, our technique, called 3D  
L 24 MP RAGE, will potentially provide significant improvements in (1)  
25 the contrast and resolution that can be obtained in a given imag-  
B 26 ing time, (2) the variety of possible image contrast behaviors,  
L 27 and (3) the flexibility of the sequence structure to be adapted  
28 to different imaging requirements. The 3D MP RAGE technique can  
29 improve the imaging capabilities in some clinical areas (e.g.,  
30 brain imaging) and provide new clinical capabilities in other  
B 31 areas (e.g., 3D abdominal imaging).

✓ 1 The method of this invention relates to a preparation-  
2 acquisition-recovery sequence cycle. The first step is mag-  
3 netization preparation (MP) period. The MP period can employ a  
4 series of RF pulses, gradient field pulses, and/or time delays to  
5 encode the desired contrast properties in the form of lon-  
6 gitudinal magnetization. At least one contrast property can be  
✓ 7 encoded by the magnetization preparation step. For example, T1-  
8 weighting combined with one of spatial or chemical presaturation  
9 can be encoded by the magnetization preparation step.

10 A data acquisition period includes at least two repetitions  
11 of a gradient echo sequence to acquire data for a fraction of  
12 k-space.

13 A magnetization recovery period is provided which allows T1  
14 and T2 relaxation before the start of the next sequence cycle.  
15 The magnetization recovery period can have a time of zero. The  
16 time period employed for magnetization recovery can also be  
17 employed for magnetization preparation.

18 The MP, data acquisition and magnetization recovery steps  
19 are repeated until a predetermined k-space volume is sampled.

✓ 20 Advantageously, at least some of the preparation-  
21 acquisition-recovery sequences cycles are initiated by a trigger  
22 signal, whereby the sequence is synchronized with an external  
23 temporal event, such as respiration or heart beat.

24 Some or all of the RF pulses and/or gradient pulses applied  
25 during any of the steps can serve the purpose of stabilizing  
26 responses of the apparatus (such as eddy currents). In addition,  
27 or instead of the foregoing, some or all of the RF pulses and/or  
28 gradient pulses can be for the purpose of stabilizing the mag-  
29 netization system, e.g., oscillations in signal strength.

30 The duration of any of the steps can be constant; alterna-  
31 tively, or in addition, the duration of at least one of the steps  
32 can vary from sequence cycle to cycle.  
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1       Some or all of the RF pulses can be spatially and/or chemi-  
2 cally selective. The spatially selectivity can be in two or  
3 three dimensions. A given pulse can combine spatial and chemical  
4 selection.

5       Some or all of the RF pulses can be spatially and/or chemi-  
6 cally non-selective.

7       The gradient-echo sequence can employ gradient or RF spoil-  
8 ing to reduce or eliminate the effects of residual transverse  
9 coherences. The gradient-echo sequence can employ a partially or  
10 fully rephased gradient structure and can employ flip angles  
11 which are constant or which vary within a given data acquisition  
12 period and/or between data acquisition periods. The gradient-  
13 echo sequence can employ an echo time and/or repetition time  
14 which is selected from the group consisting of constant, varying  
15 within a given data acquisition period, varying between data ac-  
16 quisition period, and varying both within and between data ac-  
17 quisition periods.

18       The gradient-echo sequence can employ a data sampling period  
19 which is either constant, varies within a given data acquisition  
20 period, varies between data acquisition periods, or which varies  
21 both within and between data acquisition periods. The gradient-  
22 echo sequence can employ either symmetric or asymmetric sampling  
23 of the echo thereby potentially acquiring only a half echo. The  
24 signal can be acquired in the presence of a single constant ap-  
25 plied gradient, and the remaining spatial dimensions can be  
26 phase-encoded (standard Fourier transform phase encoding).

27       Further, the gradient echo sequence can acquire a plane, or  
28 a fraction of a plane, of k-space data during each sequence  
29 cycle. Alternatively, the k-space data collected by the  
30 gradient-echo sequence during a given sequence cycle might not be  
31 contained in any plane. The temporal order in which the k-space  
32 data is collected for each sequence cycle is determined based on  
33 achieving selected properties in the image, such as contrast, or  
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1 selected properties of the corresponding point spread function.  
2 The temporal order of k-space data collection can be fixed or can  
3 vary from sequence cycle to cycle. The gradient-echo sequence  
4 can acquire a fixed or a varying amount of k-space data during  
5 each sequence cycle. The gradient-echo sequence can acquire data  
6 in the presence of from one to three time-varying applied  
7 gradients or in the presence of two or three constant applied  
8 gradients, and any remaining spatial dimensions employ standard  
9 phase encoding. The gradient-echo sequence can employ predeter-  
10 mined gradient waveforms to compensate, in the sampled signal,  
11 for phase shifts due to flow and/or motion. The compensations  
12 can be specifically designed for at least one of velocity, ac-  
13 celeration and higher orders of motion.

14 The data acquisition can be in the absence of any applied  
15 magnetic field gradients and from two to three spatial dimensions  
16 are encoded using standard phase-encoding. Thus, one dimension  
17 of the three or four dimensional data set, contains chemical  
18 shift information.

19 Objects of the Invention

20 An object of the invention is provide improved imaging  
21 capabilities and to thereby provide increased patient throughput  
22 and reduced examination costs.

23 Drawings

24 FIGURE 1 is a schematic representation of 3D MP RAGE.

25 FIGURE 2 is a timing diagram for a T1-weighted 3D MP RAGE se-  
26 quence which employs a 180° pulse followed by a delay for preara-  
27 tion, and a FLASH gradient-echo sequence for data acquisition.

28 FIGURES 3 is an images produced in accordance with Example I.

29 FIGURES 4 is an images produced in accordance with Example II.

30 FIGURE 5 is an image produced in accordance with Example III.

31 FIGURE 6 is an image produced in accordance with Example IV.

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Description of the Preferred Embodiments

2 Since its introduction into general clinical use in the  
3 early 1980's, magnetic resonance imaging (MRI) has become a very  
4 important diagnostic tool that is employed routinely in the  
5 course of patient care. In many areas, MRI has replaced X-ray  
6 computed tomography (CT) as the diagnostic imaging study of  
7 choice. Critical to the success and acceptance of MRI as a  
8 primary imaging modality has been the continued development of  
9 new pulse sequence techniques which have both improved the imag-  
10 ing capabilities in existing areas of clinical use (e.g., brain  
11 imaging) and provided new clinical areas of application (e.g.,  
12 magnetic resonance angiography). The new techniques can be clas-  
13 sified into two general categories, those which improve the imag-  
14 ing capabilities in an existing area of clinical use (e.g., brain  
15 imaging), and those which provide imaging capabilities in a new  
16 clinical area (e.g., the development of magnetic resonance an-  
17 giography techniques).

B 18 The three-dimensional (3D) MRI technique of the present in-  
19 vention employs a magnetization preparation-data acquisition  
20 -magnetization recovery cycle as the basic sequence element. Our  
21 new pulse sequence technique generalizes and extends the basic,  
B 22 prepare-acquire, philosophy introduced by Haase et al in 1989  
23 with the snapshot FLASH technique.

24 By employing a distinct magnetization preparation period,  
25 the determination of the image contrast can be largely separated  
26 from the data acquisition. The image data is acquired using a  
27 rapid gradient-echo sequence. Additional control over the image  
28 contrast is provided by varying the duration of the magnetization  
29 recovery period. For convenience, reference to the new technique  
B 30 will be by the acronym 3D MP RAGE for 3-Dimensional  
31 Magnetization-Prepared Rapid Gradient-Echo imaging.  
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L 33 1 In experiments with 3D MP RAGE, high-quality 3D image sets  
2 (128x128x256 voxels) of the abdomen, were acquired showing mini-  
B  
L 33H 3 mal respiratory artifacts in just over 7 minutes (voxel size  
4 2.7x2.7x2.7mm<sup>3</sup>), and 3D image sets (128x128x256 voxels) of the  
5 head showing excellent gray matter/white matter contrast in less  
B 33H 6 than 6 minutes (voxel size 1.0x2.0x1.4mm<sup>3</sup>). The technique of the  
B 7 instant invention can produce high-resolution 3D image sets of  
8 the abdomen with minimal respiratory artifacts in an imaging  
9 period acceptable for routine clinical use.

B 10 3D MP RAGE can be applicable as a general screening pulse  
11 sequence for certain anatomical areas, and can result in sig-  
12 nificant reductions in patient exam time, thus providing in-  
13 creased patient throughput and decreased examination costs.

14 Since the magnetization is sampled during a transient that  
15 is dependent on the tissue T1 relaxation times, many aspects of  
16 the theoretical description and optimization of the sequence are  
17 even more difficult than was the case for existing steady-state  
B 18 imaging techniques. Before the 3D MP RAGE technique could be  
19 made available for widespread clinical application, it was essen-  
20 tial that the intricacies of the contrast behavior be fully un-  
21 derstood.

CLB 22 1. Three-Dimensional Imaging

PB 23 2D versus 3D

P 24 Clinical magnetic resonance images are usually acquired as  
B 25 either a 2-dimensional (2D) plane or 3-dimensional (3D) volume of  
26 data. In either case, the image data is generally presented as a  
B 27 series of 2D slices. The reference axis determining the slice  
L 28 direction in the 3D case is based on the mechanics of the pulse  
29 sequence.

30 Each discrete intensity value (assuming a magnitude repre-  
31 sentation) in the image data represents an integral of the proton  
32 density, weighted by the T1 and T2 relaxation times, over a small  
33 volume (neglecting flow or other effects). For the standard  
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1 Effect of Multislice Interference on Image Contrast in T2- and  
B14 2 T1-weighted MR Images. AJNR 9, 443-451, 1988, and Schwaighofer  
3 BW, Kyle KY, Mattrey RF. Diagnostic Significance of Interslice  
B 4 Gap and Imaging Volume in Body MR Imaging. AJR 153, 629-632,  
L 5 1989.

6 The cross-talk between closely spaced slices can be a disad-  
B 7 vantage of 2D multi-slice acquisitions for closely spaced or con-  
8 tiguous slices, but we note that a tremendous amount of research  
9 effort has been dedicated to optimizing RF inversion, excitation,  
10 and refocusing profiles to minimize slice-to-slice interference,  
11 as disclosed for example in Warren WS, Silver M, in Advances in  
B 12 Magnetic Resonance, Academic Press, 12, 248, 1988.

13 In the 3D case (neglecting any effects of the RF pulses),  
14 the integrand for all directions is proportional to the inverse  
15 Fourier transform of the corresponding filter function in spatial  
16 frequency space. Assuming ideal conditions and no data window-  
17 ing, the multiplicative term (i.e., the point spread function or  
18 PSF) for the weighted proton density has the same form for each  
19 direction. This fact is advantageous if the image data is ac-  
B 20 quired with isotropic, or nearly isotropic, resolution and the 3D  
21 volume of data is reformatted to yield images in planes other  
22 than reference orientation. However, if the slice thickness  
23 (spacing in the second phase-encoding direction) is large com-  
24 pared to the in-plane resolution, truncation artifacts arising  
25 from the sidelobes of the PSF will be significantly worse in the  
26 slice direction as disclosed in Carlson J, Crooks L, Ortendahl D,  
✓ 27 et al., and Signal-to-Noise Ratio and Section Thickness in Two- 0  
28 dimensional versus Three-dimensional Fourier Transform MR Imag-  
B14 29 ing. Radiology 166, 266-270, 1988.

30 Truncation artifacts in the third dimension usually become  
B 31 pronounced with slice thicknesses greater than about 2 to 3mm, as  
✓ 32 disclosed in Carlson J, Crooks L, Ortendahl D, et al. Signal- 0  
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1 to-Noise Ratio and Section Thickness in Two-dimensional versus  
2 Three-dimensional Fourier Transform MR Imaging. Radiology 166,  
3 266-270, 1988.

4 Three-dimensional volume techniques can provide several ad-  
5 vantages over two-dimensional multi-slice techniques. As dis-  
6 cussed above, the 3D acquisition inherently provides contiguous  
7 slices and the functional form of the slice profile does not  
8 change with the spacing between the slices. If the 3D acquisi-  
9 tion employs isotropic, or nearly isotropic, resolution, the  
10 volume data set can be reformatted to yield high-resolution con-  
11 tiguous image slices in any arbitrary orientation, as disclosed  
12 in Lai C-M, Lauterbur PC. True Three-Dimensional Image  
13 Reconstruction by Nuclear Magnetic Resonance Zeugmatography.  
14 Phys Med Biol 5, 851-856, 1981, Buonanno FS, Pykett IL, Brady  
15 TJ, et al. Clinical Relevance of Two Different Nuclear Magnetic  
16 Resonance (NMR) Approaches to Imaging of a Low-Grade Astrocytoma.  
17 J Comput Assist Tomogr 6, 529-535, 1982, and Pykett IL, Buonanno  
18 FS, Brady TJ, Kistler JP. True Three-Dimensional Nuclear Mag-  
19 netic Resonance Neuro-Imaging in Ischemic Stroke: Correlation of  
20 NMR, X-ray CT and Pathology. Stroke 14, 173-177, 1983.

21 In a 3D acquisition, the signal-to-noise ratio increases as  
22 the square root of the number of slices, since the slices are ac-  
23 quired through phase-encoding. However, the use of a second  
24 phase-encoding direction generally increases the sensitivity of  
25 3D images to motion induced artifacts.

26 Whether 2D or 3D is more efficient in a given imaging situa-  
27 tion depends on the repetition time TR, which is chosen based on  
28 the desired contrast behavior and the properties of the pulse se-  
29 quence, and the minimum time for an excite-acquire cycle, TRmin,  
30 which is also dependent on the properties of the pulse sequence.  
31 The relative values of TR and TRmin determine how many different  
32 slice acquisitions can be time-multiplexed within TR. For the  
33 pulse sequence techniques in clinical use today, TRs greater than  
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lowed by a data acquisition period using a short-TR gradient-echo sequence. The acquisition period can employ any of the standard gradient-echo techniques, such as FLASH, GRASS or FISP, or specially modified gradient-echo techniques. The acquisition period should be relatively short compared to the T1 values of interest. The acronym applicable to the acquisition portion of this type of sequence is RAGE for rapid gradient echo. The 2D implementations of these magnetization prepared rapid gradient echo (MP RAGE) sequences have already shown very promising initial results for perfusion, cardiac and abdominal imaging. The perfusion imaging is disclosed in Finelli DA, Kiefer B, Deimling M, et al. Dynamic Contrast-Enhanced Perfusion Studies of the Brain with Snapshot FLASH. Radiology 173(P), 42, 1989 (abstract) and Atkinson DJ, Burstein D, Edelman RR. Evaluation of First-Pass Cardiac Perfusion with Instant MR Imaging. Radiology 173(P), 358, 1989 (abstract). The cardiac imaging is disclosed in Haase A, Matthaei D, Henrich D, et al. Cardiac NMR Imaging Using Snapshot FLASH NMR. "Book of Abstracts", Society of Magnetic Resonance in Medicine, 8th Annual Meeting, 56, 1989 and Finelli DA, Kiefer B, Lenz G, et al. Snapshot FLASH Imaging: Cardiac Applications. Radiology 173(P), 275, 1989 (abstract) and abdominal imaging is disclosed in de Lange EE, Mugler III JP, Gay SB, et al. "Snapshot-FLASH" Imaging of the Liver. Magn Reson Imaging 8(S1), 52, 1990 (abstract) and Edelman RR, Atkinson DJ, Wallner B, et al. Breath-Hold Abdominal STIR and T2-Weighted Imaging Using an Interleaved Ultrafast Gradient-Echo Sequence. "Works in Progress", Society for Magnetic Resonance Imaging, 8th Annual Meeting, 35, 1990.

In an MP RAGE sequence, the data acquisition occurs during a T1-dependent transient. Sampling the magnetization during a transient presents many technical problems with the design of MP RAGE sequences, analogous to some of those encountered with T2 decay in echo-planar and RARE imaging. Whereas the original

1 Fourier transform imaging technique, the data values are equally  
2 spaced along each of 2 (or 3) mutually orthogonal axes cor-  
3 responding to the read out direction and phase-encoding  
4 direction(s). In the 2D case, the integrand corresponding to the  
5 two in-plane directions is proportional to the inverse Fourier  
6 transform of any filter function applied to the spatial frequency  
7 data in the given direction. In the ideal case, assuming the  
8 data is not windowed with a smoothing function, the integrand is  
9 the weighted proton density times a sinc function, as disclosed  
10 in Bracewell RN. The Fourier Transform and its Applications, 2nd  
11 ed., McGraw-Hill, New York, 1978. For the axis perpendicular to  
12 the image plane, the integrand is the weighted proton density  
13 times the slice profile for the image, which is determined by the  
14 net effect of the radio frequency (RF) pulse or pulses in the se-  
15 quence, as disclosed in Rosen BR, Pykett IL, Brady TJ. Spin Lat-  
16 tice Relaxation Time Measurements in Two-Dimensional Nuclear Mag-  
17 netic Resonance Imaging: Corrections for Plane Selection and  
18 Pulse Sequence. J Comput Assist Tomogr 8, 195-199, 1984, Young  
19 IR, Bydder GM. Some Factors Involving Slice Shape which Affect  
20 Contrast in Nuclear Magnetic Resonance (NMR) Imaging, Ann Radiol  
21 (Paris) 28, 112-118, 1985, and Young IR, Bryant DJ, Payne JA.  
22 Variations in Slice Shape and Absorption as Artifacts in the  
23 Determination of Tissue Parameters in NMR Imaging. Magn Reson Med  
24 2, 355-389, 1985. If multiple 2D slices are acquired by time-  
25 multiplexing the acquisitions for different slice positions as is  
26 usually done in standard 2D clinical imaging, the profile for a  
27 given slice becomes increasingly distorted as the distance be-  
28 tween adjacent slices is decreased, as disclosed in Kneeland JB,  
29 Shimakawa A, Wehrli FW. Effect of Intersection Spacing on MR  
30 Image Contrast and Study Time. Radiology 158, 819-822, 1986,  
31 Crawley AP, Henkelman RM. A Stimulated Echo Artifact from Slice  
32 Interference in Magnetic Resonance Imaging. Med Phys 14, 842-  
33 848, 1987, Kucharczyk W, Crawley AP, Kelly WM, Henkelman RM.

1 approximately 100 to 200ms are usually best suited for 2D multi-  
2 slice imaging, whereas TRs significantly less than 100ms are best  
3 suited to 3D volume imaging. There is of course an intermediate  
4 region where a hybrid approach, multiple 3D volume imaging, is  
5 applicable as disclosed in Wilk RM, Harms SE. Temporomandibular  
6 Joint: Multislab, Three-Dimensional Fourier Transform MR Imaging.  
7 Radiology 167, 861-863, 1988.

3D Clinical Imaging

8 In the early 1980's, 3D imaging results were reported for  
9 excised organs and human brains in-vivo. Initial human applica-  
10 tions used saturation recovery and inversion recovery sequences,  
11 both of which employed 90° RF pulses for excitation, as disclosed  
12 in Buonanno FS, Pykett IL, Brady TJ, et al. Clinical Relevance  
13 of Two Different Nuclear Magnetic Resonance (NMR) Approaches to  
14 Imaging of a Low-Grade Astrocytoma. J Comput Assist Tomogr 6,  
15 529-535, 1982 and Pykett IL, Buonanno FS, Brady TJ, Kistler JP.  
16 True Three-Dimensional Nuclear Magnetic Resonance Neuro-Imaging  
17 in Ischemic Stroke: Correlation of NMR, X-ray CT and Pathology.  
18 Stroke 14, 173-177, 1983.

19 To achieve the desired contrast properties with these se-  
20 quences, TRs of 200ms or longer were necessary. A whole-head  
21 isotropic high-resolution (1 to 3mm) data set required imaging  
22 times of 19 to 46 minutes. Although the initial expectations for  
23 3D volume acquisitions were very high, the development and  
24 refinement of 2D multi-slice methods, combined with the rela-  
25 tively long imaging times required for high-resolution large-  
26 volume 3D acquisitions, diminished clinical interest in 3D tech-  
27 niques for several years.

28 For the in-plane image matrix sizes commonly employed (128  
29 or 256), a TR of less than 100ms is required for high-resolution  
30 large-volume (e.g., 64 or more phase-encoding steps in the third  
31 dimension) 3D image sets to be acquired in clinically reasonable  
32 times (less than approximately 15 minutes). This sequence re-  
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quirement was met with the introduction in the mid-1980s of the short-TR, partial flip angle gradient-echo sequences, such as FLASH, FFE, GRASS, FAST and FISP. FLASH is disclosed in Haase A, Frahm J, Matthaei D, et al., FLASH Imaging. Rapid NMR Imaging Using Low Flip-Angle Pulses. J Magn Reson 67, 258-266, 1986, and FFE is disclosed in Van der Meulen P, Groen JP, Cuppen JJM. Very Fast MR Imaging by Field Echoes and Small Angle Excitation. Magn Reson Imaging 3, 297-299, 1985. GRASS is disclosed in Utz JA, Herfkens RJ, Glover G, Pelc N. Three Second Clinical NMR Images Using a Gradient Recalled Acquisition in a Steady State Mode (GRASS). Magn Reson Imaging 4, 106, 1986 (abstract), and FAST is disclosed in Gyngell ML. The Application of Steady-State Free Precession in Rapid 2DFT NMR Imaging: FAST and CE-FAST Sequences. Magn Reson Imaging 6, 415-419, 1988. FISP is disclosed in Oppelt A, Graumann R, Barfuss H, et al. FISP - a New Fast MRI Sequence. Electromedica 54, 15-18, 1986. For example, a TR of 15ms and a flip angle of 15° produced 128<sup>3</sup> image sets of human hands and feet in only 4 minutes, as disclosed in Frahm et al. (Frahm J, Haase A, Matthaei D. Rapid Three-Dimensional MR Imaging Using the FLASH Technique. J Comput Assist Tomogr 10, 363-368, 1986). Three-dimensional sequences, dominated by the 3D gradient-echo techniques, have shown promising results for clinical application in the head as disclosed in Runge VM, Wood ML, Kaufman DM, et al. FLASH: Clinical Three-Dimensional Magnetic Resonance Imaging. Radiographics 8, 161, 1988, Hu XP, Tan KK, Levin DN, et al. Three-Dimensional Magnetic Resonance Images of the Brain: Application to Neurosurgical Planning. J Neurosurg 72, 433-440, 1990), in the spine, as disclosed in Gallimore GW Jr, Harms SE. Selective Three-Dimensional MR Imaging of the Spine. J Comput Assist Tomogr 11, 124-128, 1987 and Sherry CS, Harms SE, McCroskey WK. Spinal MR Imaging: Multiplanar Representation from a Single High Resolution 3D Acquisition. J Comput Assist Tomogr 11, 859-862, 1987, and Tsuruda JS, Norman D, Dillon W, et al.

1 Three-Dimensional Gradient-Recalled MR Imaging as a Screening  
B 14 2 Tool for the Diagnosis of Cervical Radiculopathy. AJR 154, 375-  
L 3 383, 1990. The use in joints, is disclosed in Wilk RM, Harms SE.  
4 Temporomandibular Joint: Multislab, Three-Dimensional Fourier  
B 14 5 Transform MR Imaging. Radiology 167, 861-863, 1988, Harms SE,  
6 Muschler G. Three-Dimensional MR Imaging of the Knee Using Sur-  
B 14 7 face Coils. J Comput Assist Tomogr 10, 773-777, 1986, Tyrell RL,  
8 Gluckert K, Pathria M, Modic MT. Fast Three-Dimensional MR Imag-  
B 9 ing of the Knee: Comparison with Arthroscopy. Radiology 166,  
L 10 14 865-872, 1988, Spritzer CE, Vogler JB, Martinez S, et al. MR Im-  
B 11 aging of the Knee: Preliminary Results with a 3DFT GRASS Pulse  
L 14 12 Sequence. AJR 150, 597-603, 1988, Haggar AM, Froelich JW, Hear-  
B 13 shen DO, Sadasivan K. Meniscal Abnormalities of the Knee: 3DFT  
L 14 14 fast-scan GRASS MR Imaging. AJR 150, 1341-1344, 1988 and Solomon  
15 SL, Totty WG, Lee JK. MR Imaging of the Knee: Comparison of  
16 Three-Dimensional FISP and Two-Dimensional Spin-Echo Pulse Se-  
B 14 17 quences. Radiology 173, 739-742, 1989, Harms SE, Flamig DP,  
18 Fisher CF, Fulmer JM. New Method for Fast MR Imaging of the Knee.  
B 14 19 Radiology 173, 743-750, 1989. Other applications include mag-  
20 netic resonance angiography.

B 21 The 3D short-TR gradient-echo sequences can be divided into  
22 two general categories, those which employ a steady state of only  
23 the longitudinal component of the magnetization vector (e.g.,  
24 FLASH, FFE) and those which employ a steady state of the complete  
25 magnetization vector (e.g., GRASS, FAST, FISP). The major practi-  
26 cal difference between the two sequence categories is the result-  
27 ing image contrast properties as disclosed in van der Meulen P,  
28 Groen JP, Tinus AMC, Bruntink G. Fast Field Echo Imaging: An  
B 14 29 Overview and Contrast Calculations. Magn Reson Imaging 6, 355-  
L 30 368, 1988) and Tkach JA, Haacke EM. A Comparison of Fast Spin  
B 31 Echo and Gradient Field Echo Sequences. Magn Reson Imaging 6,  
L 14 32 373-389, 1988. It is important to note that the 3D implementa-  
33 tions of the longitudinal steady-state sequences, which are  
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1 employed if T1-weighted contrast is desired, have been prone to  
2 slice-to-slice intensity banding artifacts as disclosed in Wood  
3 ML, Runge VM. Artifacts Due to Residual Magnetization in Three-  
4 Dimensional Magnetic Resonance Imaging. Med Phys 15, 825-831,  
5 1988. In these sequences, some type of spoiling is employed to  
6 destroy the coherence of the transverse magnetization after the  
7 echo signal is sampled. Therefore, the transverse magnetization  
8 generated by a given excitation pulse contributes only to the  
9 signal measured in the echo period immediately following the  
10 pulse. This is the ideal case, and if the spoiling is incomplete  
11 the residual transverse magnetization may create artifacts in the  
12 image. Traditionally, various combinations of magnetic field  
13 gradients have been employed in an attempt to eliminate these ar-  
14 tifacts as disclosed in Wood ML, Runge VM. Artifacts Due to  
15 Residual Magnetization in Three-Dimensional Magnetic Resonance  
16 Imaging. Med Phys 15, 825-831, 1988 and Frahm J, Hanicke W, Mer-  
17 boldt K-D. Transverse Coherence in Rapid FLASH NMR Imaging. J  
18 Magn Reson 72, 307-314, 1987 and Wood ML, Silver M, Runge VM.  
19 Optimization of Spoiler Gradients in FLASH MRI. Magn Reson Imag-  
20 ing 5, 455-463, 1987 and Crawley AP, Wood ML, Henkelman RM.  
21 Elimination of Transverse Coherences in FLASH MRI. Magn Reson Med  
22 8, 248-260, 1988. However, gradients alone generally have been  
23 found to be incapable of totally preventing the artifacts in the  
24 3D case.

25 More recently, RF spoiling has been suggested as a method to  
26 eliminate these transverse coherence artifacts, as disclosed, for  
27 example in Crawley AP, Wood ML, Henkelman RM. Elimination of  
28 Transverse Coherences in FLASH MRI. Magn Reson Med 8, 248-260,  
29 1988. Zur Y, Bendel P. Elimination of the Steady State Trans-  
30 verse Magnetization in Short TR Imaging. "Book of Abstracts",  
31 Society of Magnetic Resonance in Medicine, 6th Annual Meeting,  
32 440, 1987. Zur Y, Wood ML, Neuringer LJ. Spoiling of Transverse  
33 Coherences without Spoiler Gradients. "Book of Abstracts",  
34

B  
L 1 Society of Magnetic Resonance in Medicine, 9th Annual Meeting,  
2 31, 1990, Murdoch JB. An Analysis of RF Phase Shift Spoiling and  
3 Its Effect on Contrast. "Works-in-Progress", Society of Magnetic  
B 4 Resonance in Medicine, 9th Annual Meetin, 1305,1990. This tech-  
5 nique is now available on the imagers from several commercial  
6 vendors and clinical evaluations of the technique have begun as  
7 disclosed in Foo TKF, Bernstein MA, Holsinger AE, et al.  
8 UltraFast Spoiled Gradient Recalled (SPGR) Image Acquisition.  
9 "Works-in-Progress", Society of Magnetic Resonance in Medicine,  
B 10 9th Annual Meeting, 1308, 1990.

11 Another class of sequences that have played a minor role in  
B  
L 12 3D imaging are the spin-echo sequences which employ pulse angles  
13 other than 90° for the RF excitation pulse as disclosed in Tkach  
14 JA, Haacke EM. A Comparison of Fast Spin Echo and Gradient Field  
B14 15 Echo Sequences. Magn Reson Imaging 6, 373-389, 1988 and Mugler  
16 III JP, Brookeman JR. Rapid 3D Spin-Echo Imaging Using Large  
17 Flip Angle Excitation. Magn Reson Imaging 6(S1), 53, 1988  
3 B 18 (abstract). These sequences can provide TR's of 100ms or  
19 slightly less, yielding much more reasonable 3D acquisition times  
B14 20 than the standard 90°-180° sequences. The 3D spin-echo sequences  
21 of course provide the advantage of a decreased sensitivity to ar-  
22 tifacts from field inhomogeneities and susceptibility changes in  
23 comparison to their gradient echo counterparts. At higher field  
24 strengths, however, power deposition may be a problem due to the  
B 25 closely spaced 180° pulses. These 3D spin-echo sequences have  
26 not yet found widespread application.

~~P~~ P27 Magnetization Prepared Imaging

P 28 The vast majority of pulse sequences in clinical use today  
29 employ a steady-state acquisition. This may be in the form of a  
30 steady state of the longitudinal component of the magnetization  
31 vector (e.g., spin-echo or FLASH) or of the complete magnetiza-  
32 tion vector (e.g., GRASS or FISP). In either case, each line  
33 (assuming a Fourier transform method) of spatial frequency space  
34



1 is equivalently weighted with respect to the tissue relaxation  
2 parameters. There are some notable exceptions which sample the  
3 magnetization during a transient, for example Echo-Planar, Hybrid  
4 imaging and RARE imaging, but these techniques have not yet found  
5 widespread clinical use. Echo-Planar is disclosed in Mansfield  
6 P. Multi-Planar Image Formation Using NMR Spin Echos J Phys C 10,  
7 L55, 1977. Hybrid imaging is disclosed in Haacke EM, Bearden FH,  
8 Clayton JR, Linga NR. Reduction of MR Imaging Time by the Hybrid  
9 Fast-Scan Technique. Radiology 158, 521-529, 1986 and RARE imag-  
10 ing is disclosed in J, Nauerth A, Friedburg H. RARE Imaging: A  
11 Fast Imaging Method for Clinical MR. Magn Reson Med 3, 823-833,  
12 1986.

13 A pulse sequence technique, called snapshot FLASH imaging,  
14 is initiated by some type of contrast preparation, followed by a  
15 very rapid, or snapshot, FLASH image acquisition. The use of a  
16 distinct magnetization preparation period largely separates the  
17 generation of the image contrast from the acquisition of the  
18 image data. Haase's snapshot FLASH sequence acquired a 64x128  
19 image in less than 200ms. The speed of this technique clearly  
20 makes it suitable for imaging certain dynamic processes or for  
21 reducing flow and motion artifacts. Decoupling the contrast  
22 preparation from the acquisition potentially provides many inter-  
23 esting applications. It is noted that the use of a contrast  
24 preparation followed by a rapid acquisition has also been  
25 demonstrated with echo-planar imaging as disclosed in Stehling  
26 MK, Ordidge RJ, Coxon R, et al. Ultra-High-Speed Inversion  
27 Recovery Echo Planar MR Imaging: Technique and Application.  
28 Radiology 169(P), 377, 1988 (abstract). Stehling MK, Ordidge RJ,  
29 Coxon R, Mansfield P. Inversion-Recovery Echo-Planar Imaging  
30 (IR-EPI) at 0.5T. Magn Reson Med 13, 514-517, 1990.

31 The snapshot FLASH technique is the first member of a  
32 rapidly growing new family of pulse sequences which employ as the  
33 basic sequence element a magnetization preparation period fol-  
34

1 technique of Haase acquires the complete image data in one-shot,  
2 there have already been extensions as disclosed in Edelman RR,  
3 Atkinson DJ, Wallner B, et al. Breath-Hold Abdominal STIR and  
4 T2-Weighted Imaging Using an Interleaved Ultrafast Gradient-Echo  
5 Sequence. "Works in Progress", Society for Magnetic Resonance  
6 Imaging, 8th Annual Meeting, 35, 1990 and Bottcher U, Norris D,  
7 Leibfritz D. Sequential Inversion Recovery Snapshot-FLASH. Magn  
8 Reson Imaging 8(S1), 16, 1990 (abstract) to collecting the data  
9 for a 2D image in several distinct prepare-acquire cycles (i.e. a  
10 multi-shot approach), thus reducing the effects of the transient  
11 acquisition on the image contrast by employing a set of shorter  
12 RAGE acquisitions in place of the original longer RAGE acquisi-  
13 tion.

14 Similar to earlier developments in echo-planar and RARE im-  
15 aging, reordered phase encoding was investigated as an alterna-  
16 tive approach to reducing the deleterious effects of T1 decay  
17 during the acquisition. Reordered phase encoding can provide an  
18 improved point spread function and a substantial increase in the  
19 CNRs as disclosed in Mugler III JP, Spraggins TA. Improving  
20 Image Quality in Snapshot FLASH and 3D MP RAGE Sequences by  
21 Employing Reordered Phase Encoding. "Works-in-Progress" Society  
22 of Magnetic Resonance in Medicine, 9th Annual Meeting, 1310,  
23 1990.

24 The straight forward application of the snapshot FLASH tech-  
25 nique to a one-shot 3D acquisition results in a measuring time of  
26 only a few seconds for a complete 3D data set as disclosed in  
27 Henrich D, Haase A, Matthaei D. Fast Three-Dimensional Snapshot  
28 FLASH MR Studies. Radiology 173(P), 289, 1989 (abstract). The  
29 multi-shot 3D approach, of the instant invention, known as 3D MP  
30 RAGE as disclosed in Mugler III JP, Brookeman JR. Three-  
31 Dimensional Magnetization-Prepared Rapid Gradient-Echo Imaging  
32  
33  
34

B 14 1 (3D MP RAGE). Magn Reson Med 15, (152-157), 1990, has produced  
L 2 high-contrast, high-resolution 3D image sets in a period of  
3 several minutes.

✓ 4 Generalizing and extending the work of Haase et al on snap-  
5 shot FLASH to the general three dimensional case presented  
6 several problems. For example, due to the structure and com-  
B 7 plexity of our technique, 3D MP RAGE, the contrast behavior of  
8 the images displays a complicated dependence on many sequence  
9 parameters. The snapshot FLASH technique which employs repeti-  
B 10 tion times for the gradient-echo sequence on the order of 5ms or  
L 11 less and flip angles of 5° or less, was designed to acquire an  
12 image or images very rapidly in comparison to existing routine  
13 clinical techniques. The snapshot FLASH technique is disclosed  
14 in Haase A, Matthaei D, Bartkowski R, et al. Inversion Recovery  
B 15 Snapshot FLASH MR Imaging, J Comput Assist Tomogr 13, 1036-1040,  
16 1989. Haase A. Snapshot FLASH MRI, and Applications to T1, T2,  
14 17 and Chemical-Shift Imaging. Magn Reson Med 13, 77-89, 1990. The  
L 33 18 original published work demonstrated 64x128 images acquired in  
B 19 approximately 200ms. As presented by Haase, the combination of  
20 the very short acquisition time and the minimal effect of a  
21 series of very low flip angle pulses on the longitudinal mag-  
22 netization allowed the snapshot FLASH technique to be used in  
23 combination with specific contrast preparations and yield mean-  
24 ingful imaging results. It is noted that the experimental work  
B 25 of Haase was performed on a 40cm. bore 4.7 Tesla imager, that is,  
26 a nonclinical machine.

✓ 27 When the snapshot FLASH technique was implemented on whole-  
28 body machines, results similar to those demonstrated by Haase  
29 were obtained, as disclosed in Kiefer B, Deimling M, Finelli D.  
30 Ultrafast Measurement of T1- and T2-weighted Images with  
B 31 "SNAPSHOT"-FLASH. Book of Abstracts, 8th Annual Meeting of the  
L 32 Society of Magnetic Resonance in Medicine, 1989, p 367. However,  
33 due to the very low flip angles and to the high sampling  
34

1 bandwidth secondary to the very short repetition time, the signal  
2 to noise ratios per volume of these images were very low compared  
3 to those for the spin-echo or gradient-echo techniques routinely  
4 employed in clinical imaging. If the sequence were simply  
B 5 repeated, as in a direct transformation to a 3D multi-shot im-  
6 plementation, some improvement in the signal-to-noise would of  
7 course result due to the second phase-encoding direction. However  
8 the contrast properties would be greatly affected due to the  
9 repeated application of the preparation and acquisition, and for  
10 more than a very few cycles the advantage of a very short total  
11 scan time would be lost. The short scan time was the primary im-  
12 petus behind the magnetization prepared snapshot FLASH technique.  
13 Thus, it appeared that the potential role of the magnetization  
14 prepared snapshot FLASH technique was imaging moving structures  
15 or dynamic processes with relatively high temporal resolution and  
16 freely controllable image contrast. It was not obvious that some  
17 sort of extension to a multi-shot three-dimensional imaging  
18 strategy would yield results of any particular value.

19 One of the important modifications introduced in developing  
B 20 our technique 3D MP RAGE, was to employ significantly longer  
21 repetition times and larger flip angles. One specific purpose of  
22 the longer repetition time is to allow data sampling with a sub-  
23 stantially decreased bandwidth as compared to the snapshot FLASH  
24 sequence. Although it is well known that taken separately  
25 decreased bandwidths and increased flip angles would be ap-  
26 plicable for increased signal-to-noise ratios, the effectiveness  
27 of such an approach in this case was not obvious because of the  
28 problems that would accompany such modifications. Specifically,  
29 a significantly longer repetition time would in turn sig-  
30 nificantly lengthen the period of data acquisition, allowing  
31 relaxation to play a major role in the measured signals. Thus the  
32 signal strengths would depend on the phase-encoding step and as-  
33 sumably result in undesirable image degradation. In addition,  
34

1 larger flip angles would result in the data acquisition having a  
2 significant affect on evolution of the magnetization. This  
3 process would introduce further variations in the signal strength  
4 as a function of the phase-encoding step, presumably leading to  
5 additional image degradation. It has now been discovered that  
6 longer repetition times and larger flip angles could be success-  
7 fully employed if the sequence structure was properly designed.  
8 By "successfully employed", is meant that only minimal image  
9 degradation results. It been further discovered that such a  
10 structure could be used to produce three dimensional image sets  
11 of sufficient image quality to be useful in routine clinical  
12 evaluations.

B  
L 13 The 3D MP RAGE technique differs philosophically from snap-  
14 shot FLASH in that 3D MP RAGE was designed to acquire image data  
15 with high spatial resolution, high signal-to-noise, but low tem-  
16 poral resolution where snapshot FLASH was designed to trade  
17 signal-to-noise and spatial resolution for very high temporal  
B 18 resolution. In addition, in developing 3D MP RAGE we violated the  
19 basic precepts of snapshot FLASH, namely the ultrashort repeti-  
20 tion times and very low flip angles.

P  
L B 21 **T1 contrast**

22 As is well known from both NMR spectroscopy and MRI, a 180°  
23 inversion pulse followed by a time delay is an effective prepara-  
24 tion for developing T1-dependent contrast. However, depending on  
25 the overall sequence timing and constraints, and the tissue  
B 26 properties, flip angles other than 180° may provide optimum SNR  
27 and/or CNR. A T1 preparation is implemented which consists of an  
60 B 28  $\alpha^\circ$  pulse  $0 < \alpha^\circ < 180$ ) followed by a time delay. If the delay is  
29 short compared to T2 values of interest, spoiling gradients are  
30 applied during the delay period to eliminate or minimize image  
31 artifacts from residual transverse magnetization.

P  
LB  
1 T2 contrast

2 A 90°-delay-180°-delay-90° preparation can encode T2 con-  
3 trast in the form of longitudinal magnetization. Depending on  
4 the relative phases of the pulses, the encoded magnetization can  
5 be placed along the positive z-axis (i.e., a driven equilibrium  
6 preparation as in the DEFT technique from NMR spectroscopy as  
7 disclosed in Becker ED, Ferretti JA, Farrar TC. Driven Equi-  
8 librium Fourier Transform Spectroscopy. A New Method for Nuclear  
B 14 9 Magnetic Resonance Signal Enhancement. J Am Chem Soc 91, 7784-  
L 10 7785, 1969) or the negative z-axis (i.e., a driven inversion  
11 preparation as disclosed in Conturo TE, Beth AH, Kessler RM, et  
12 al. Cooperative T1 and T2 Effects on Contrast and T2 Sensitivity  
13 with Improved Signal to Noise Using a New Driven Inversion Spin  
14 Echo (DISE) Sequence. "Book of Abstracts", Society of Magnetic  
B 15 Resonance in Medicine, 6th Annual Meeting, 807, 1987). Consider-  
16 ing in-vivo tissue T1 relaxation times, typical whole-body MRI  
17 gradient performance characteristics, and the resolution require-  
18 ments for clinical imaging, the image acquisition period may be  
19 comparable to some of the tissue T1 values. Thus, depending on  
20 the amount of image data acquired during a given sequence cycle,  
31 21 the starting position (+z versus -z) for the encoded magnetiza-  
22 tion can significantly affect the resulting image contrast. The  
23 amount of data acquired per cycle is dependent on the required  
24 total imaging time and the desired image resolution. Since the  
25 T1 and T2 values are usually correlated, the T1 decay during the  
26 image acquisition period opposes the T2 contrast developed by the  
27 contrast preparation if the encoded magnetization is placed along  
28 the positive z-axis. However, if the encoded magnetization is  
29 placed along the negative z-axis, the T1 decay during acquisition  
H21 30B adds to the prepared T2 contrast (assuming  $M_z < 0$ ).

*P*<sub>1</sub>  
*P*  
*B* 1 **Mixed contrast.**

2 As discussed in the preceding paragraph, the inherent sen-  
3 sitivity of the 3D MP RAGE technique to T1 decay can present  
4 problems when the goal is to produce T2-dependent contrast in the  
5 image. For certain imaging goals however, such as increased con-  
6 spicuity of liver metastases, it may be desirable to intention-  
7 ally combine the T1 and T2 contrast in the preparation. This is  
8 easily achieved by inserting a variable delay period between the  
*B* 9 second 90° pulse of the T2 preparation and the start of the  
10 gradient-echo acquisition.

11 Later in the sequence development, other magnetization  
12 preparations such as chemical species specific saturation may  
13 also be investigated.

*P*<sub>1</sub>  
*P*  
*B* 14 **The image acquisition period.**

15 The image data is acquired using a short-TR gradient-echo  
16 sequence. This sequence may be any one of the standard  
17 gradient-echo techniques such as FLASH, FFE, GRASS, FAST or FISP,  
18 or some variant of these sequences as described below. One of  
*B* 19 the important and interesting features of a 3D MP RAGE sequence  
20 is that the image data is acquired during a T1-dependent tran-  
21 sient. As a result, the configuration of the gradient-echo ac-  
22 quisition is critical in determining the image properties. The  
23 T1 decay during acquisition not only modifies the signal and con-  
24 trast state defined by the magnetization preparation, but also  
25 results in a T1-dependent point spread function (PSF) in the  
26 phase-encoding direction corresponding to the rapid acquisition.  
27 (If a gradient rephased sequence is employed for acquisition, the  
28 signal transient and PSF also depend on T2). Thus, it is impor-  
29 tant to explicitly account for the phase-encoding process in the  
30 theoretical calculations. Since the major structure of the image  
31 is determined by the values of the low spatial frequency com-  
32 ponents, we calculate the signal levels for given tissues based  
33 on the value of the zero spatial frequency component. The varia-  
34

tions in the spatial frequency component values with respect to zero spatial frequency define a filter function used to calculate the tissue specific PSF. The image resolution in the corresponding direction can be corrected for the effects of this PSF. Of course, the image acquisition period per cycle can be made very short to minimize these problems, but as the amount of data collected per cycle decreases so does the advantage of 3D MP RAGE over standard three-dimensional imaging techniques such as 3D FLASH. In addition, if less than a complete plane of spatial frequency space is sampled during a given sequence cycle, discontinuities may exist in the spatial frequency filter function, depending on the details of the spatial frequency sampling. Specific acquisition sequence parameters that should be included in the model of the acquisition sequence are as follows:

**TR, TE,  $T_s$**

The sequence repetition time (TR), echo time (TE), and data sampling period ( $T_s$ ) are the basic timing parameters for the gradient-echo acquisition. Since the TR is of necessity required to be short (somewhere between the hardware minimum based on the required resolution and about 20ms), a small change in TR may translate into a large fractional change in the data sampling period and hence a significant change in the noise contribution to the image.

**Flip angle.**

The choice of the flip angle for the RF excitation pulse in the gradient-echo sequence represents a trade-off between increasing the signal strength corresponding to a given phase-encoding step and increasing the effects of the acquisition on the relaxing magnetization. The employment of a constant flip angle for the acquisition, as disclosed in Mugler III JP, Brookeman JR, may not yield optimum results in all situations. Three-Dimensional Magnetization-Prepared Rapid Gradient-Echo Imaging (3D MP RAGE). Magn Reson Med 15, (152-157), 1990. The



1 theoretical model includes a flip angle that is variable as a  
2 function of the phase-encoding step. By proper choice of the  
3 flip angle values, the shape of the tissue dependent PSF can be  
4 controlled. In optimizing the sequence we would try to derive a  
5 flip angle combination that would provide well-behaved (i.e.,  
6 real, symmetric, relatively low amplitude sidelobes) PSFs and at  
7 the same time minimize the net effect of the acquisition on the  
8 relaxing magnetization within the CNR and resolution constraints.  
9 We note that a TR dependent on the phase-encoding step may also  
10 be important for achieving this goal.

*P<sub>~</sub>*  
*P*  
11 **Phase-encoding order.**

12 The order of the phase-encoding is critical in determining  
13 the contrast properties of the image. Various phase-encoding  
14 schemes have been successfully employed in previous MR techniques  
15 such as respiratory ordered phase encoding as disclosed in Bailes  
16 DR, Gilderdale DJ, Bydder GM, et al. Respiratory Ordered Phase  
17 Encoding (ROPE): A Method for Reducing Respiratory Motion Ar-  
*B 14* 18 tefacts in MR Imaging. J Comput Assist Tomogr 9, 835-838, 1985  
19 and RARE imaging. The modification of the phase-encoding order  
20 to improve the characteristics of the point spread function and  
21 provide access to a wider range of image contrast properties is  
22 discussed in Mugler III JP, Spraggins TA. Improving Image  
*B* 23 Quality in Snapshot FLASH and 3D MP RAGE Sequences by Employing  
24 Reordered Phase Encoding. "Works-in-Progress" Society of Magnetic  
*B* 25 Resonance in Medicine, 9th Annual Meeting, 1310, 1990.

*P<sub>~</sub>*  
*P*  
26 **The magnetization recovery period.**

27 The recovery period provides an additional degree of freedom for  
28 controlling the image contrast by providing additional time for  
29 T1 and T2 relaxation before the start of the next sequence cycle.  
30 The duration of the recovery period is determined by the desired  
31 contrast properties of the image, the T1 relaxation properties of  
32 the tissues, and the state of the longitudinal magnetization at  
33 the end of the gradient-echo acquisition. The two limiting cases  
34

1 for the magnetization recovery period are zero duration and a  
2 duration which is relatively long compared to the T1s of inter-  
3 est. The second case, that of a relatively long recovery period,  
4 is particularly interesting since in this case a given  
5 preparation-acquisition-recovery cycle is decoupled from other  
6 cycles, and relative variations in the recovery periods would  
7 therefore not adversely affect the image quality.

CLB 8 2. Optimization of Pulse Sequence Parameters

P 9 As one can see from the outline of the theoretical model,  
10 numerous parameters combine to determine the image SNR and CNR  
B 11 behavior in 3D MP RAGE sequences. (Even for the very simple case  
12 of an inversion recovery preparation, fixed flip angle acquisi-  
B 13 tion, and a specific phase-encoding scheme, there are 6  
14 variables.) In addition, many of the parameters are coupled and  
15 constrained based on requirements on the total imaging time, min-  
16 imum resolution, maximum chemical shift artifact, and so on.  
17 Some imaging applications require only simple optimization goals  
18 such as maximizing the SNR from a single tissue, or the CNR for a  
19 single tissue pair, subject to the other imaging requirements and  
20 constraints. However, given the complexity of the human body,  
21 such simple requirements are not always sufficient. For example,  
22 a very reasonable goal would be to maximize the CNR for one  
23 tissue pair while minimizing the signal from one or more other  
24 tissues. Thus, it will be necessary for the optimization tech-  
25 nique to search for maxima or minima based on multiple, possibly  
26 interrelated goals. For the situation described, optimization by  
27 global search would be far too time consuming. The routine  
28 employed must handle a multi-dimensional, nonlinear, constrained  
29 optimization and complicated goal functions. Traditional op-  
30 timization strategies such as direction-set methods or conjugate  
31 gradient methods, are not suited to this type of problem are dis-  
32 closed in Brent RP. Algorithms for Minimization without Deriva-  
33  
34

1 tives, Prentice-Hall, Englewood Cliffs, NJ, 1973 and Jacobs DAH,  
2 ed. The State of the Art in Numerical Analysis, Academic Press,  
3 London, 1977.

4  
CLB 5 3. Comparison with Existing 3D Imaging Techniques

PB 6 Advantages of the 3D MP RAGE technique include:

- LB 7 1. In initial imaging studies, 3D MP RAGE appears to deliver  
8 significant increases in the contrast-to-noise ratio per unit  
9 time for certain imaging situations (e.g., T1-weighted brain  
10 imaging).
- PB 11 2. The use of a separate magnetization preparation period al-  
12 lows the selection of the image contrast to be largely separated  
13 from the image data acquisition. In addition, certain tissue  
14 contrast properties can be obtained in a much shorter imaging  
15 time than is possible with existing steady-state acquisition  
16 schemes.
- PB 17 3. The cyclic nature of the sequence makes it naturally ap-  
18 plicable to imaging structures subject to periodic motion such as  
19 the liver or heart by applying a respiratory or cardiac trigger  
20 to the preparation - acquisition - relaxation cycle.
- PB 21 4. The dead times in the magnetization preparation and/or  
22 recovery periods can be used for secondary magnetization prepara-  
23 tions such as spatial or chemical presaturation.
- PB 24 5. In certain configurations of the sequence, the 3D image set  
25 shows ghosting artifacts from cardiac and respiratory motion only  
26 in one phase-encoding direction, not two phase-encoding direc-  
27 tions as is common for existing 3D imaging techniques.

28  
CCB 29 4. Specific contributions for the 3D MP RAGE technique.

- PB 30 1. Reduction of patient imaging times and examination costs.  
31 Current imaging times for brain studies at our institution range  
B 32 from 30 to 45 minutes. Often, it is necessary to repeat a  
33 specific type of sequence (e.g., T1 weighted) in multiple planes  
34

B 1 to obtain the desired anatomical views. If a high-resolution 3D  
2 volume set were available, any arbitrary view could be obtained  
3 by post-processing the image data. With the preliminary versions  
B 4 of our new technique, we can acquire 128 T1-weighted, thin con-  
L 5 tiguous slices spanning the whole head in only 6 minutes. From  
6 this set, we have obtained images in various orientations  
7 (including oblique and double oblique) using post-processing  
B 8 software built into our commercial imager. Thus, a single 3D MP  
9 RAGE acquisition could be employed as a general screening se-  
10 quence to replace two or more conventional acquisitions, reducing  
11 the imaging time for applicable studies and therefore making  
12 these studies more tolerable for the patients. In addition,  
13 since decreased imaging times can be translated into increased  
14 patient throughput, this could potentially result in a decrease  
15 in examination costs.

PB 16 2. Surgical Planning. It is well known that multi-planar  
17 images, such as those generated by CT or MRI, can be utilized to  
18 produce volume reconstructions for surgical planning. For op-  
B 19 timum results, a 3D data set of the complete region of interest  
20 with relatively high resolution is needed. The acquisition time  
B 21 for such 3D MRI data sets is typically 10 to 20 minutes using ex-  
22 isting pulse sequence techniques. Considering that the resolu-  
23 tion in such images is on the order of 1mm or less, it is often  
24 difficult for the patient to remain sufficiently still during the  
B 25 examination. In addition, with an imaging time of up to 20  
26 minutes, this type of sequence may be considered too long to be  
27 an add-on to a standard MRI exam and may therefore necessitate  
B 28 the time and expense of a separate study. The 3D MP RAGE se-  
L 29 quence, which can acquire a high-contrast, high-resolution 3D  
30 data set in only 6 minutes, is short enough to be used as an  
31 add-on to a standard examination. Thus, it should be viable to  
32 acquire the data necessary for surgical planning on a routine  
33 basis.  
34

1 Three-Dimensional Abdominal Imaging.

PB 2 The basic acquisition structure of 3D MP RAGE makes it in-  
3 herently applicable to imaging structures subject to periodic mo-  
4 tion such as the liver. In preliminary studies, we have acquired  
B 5 high-quality 3D data sets which span the entire abdomen. The  
6 images show only minimal respiratory artifacts. The acquisition  
B 7 of a 3D data set with only minimal motion artifacts is possible  
8 because the actual data acquisition occurs only at end expira-  
9 tion, when the abdomen is relatively still, and the remainder of  
10 the respiratory period is used for contrast preparation and mag-  
B 11 netization recovery. This technique can produce 3D image sets of  
12 the abdomen with minimal respiratory artifacts in an imaging  
13 period acceptable for routine clinical use.  
14

CL 15 EXAMPLE I

P 16 Imaging was performed on a standard whole-body imager operating  
B 17 at a field strength of 1.5T (Siemens Magnetom 63SP, Siemens Medi-  
L 18 cal Systems, Iselin, NJ). Figure 3 shows images from a 3D MP  
19 RAGE acquisition through the abdomen of a normal volunteer in the  
B 20 sagittal orientation. The image matrix was 128 (350mm) by 128  
21 (350mm) by 256 (700mm). This yields cubic voxels 2.7mm on a  
22 side. The total imaging time was 7.18 min. The magnetization  
L 23 preparation consisted of an inversion pulse followed by a 350ms  
24 delay which produced strong T1 weighting in the image. Each RAGE  
B 25 acquisition acquired 128 lines in 1024ms (TR/TE 8/3.3, FLASH type  
26 sequence, 10° flip angle) and was performed at end expiration.  
L 27 The recovery period was 2 s. Respiratory triggering was not used  
28 and instead, the subject voluntarily respired in synchrony with  
I 14 29 the sequence. Figures 3b-3d show coronal (b and c) and trans-  
30 verse (d) images reformatted from the original sagittal acquisi-  
B 31 tion. Since each RAGE acquisition was only 1 s, image artifacts  
32 from stomach, bowel, and cardiac motions appear predominantly in  
I 33 one phase-encoding direction (horizontal in Fig. 3a). Note the  
34

I 14 1 sharp definition of the upper edge of the liver in Figs. 3a-3c.  
L 2 Examination of the anterior subcutaneous fat in Figs. 3a and 3d  
3 reveals only minor artifacts from respiration. Note the rela-  
I 4 tively black appearance of flowing blood as seen in Fig 3c. This  
5 feature may prove very valuable in relation to studies of vessels  
6 diseased with atherosclerosis.  
7

CL 8 EXAMPLE II  
PB 9

10 Figure 4 shows images from a 3D MP RAGE acquisition of the head  
11 of a normal volunteer acquired in the sagittal orientation. The  
B 12 image matrix was 128 (180mm) by 128 (250mm) by 256 (250mm), in-  
33 13 terpolated to 128x256x256. This yields voxels with dimensions of  
14 1.4 by 1.0 (interpolated) by 1.0mm. The total imaging time was  
15 5.92 min. The magnetization preparation consisted of an inver-  
B 16 sion pulse followed by a 500ms delay which produced strong T1  
17 weighting in the image. Each RAGE acquisition acquired 128 lines  
18 I 18 14 The recovery period was 1 s. Figures 4b-4d show coronal (b and  
19 c) and transverse (d) images reformatted from the original sagit-  
20 tal acquisition. The images display excellent gray/white con-  
21 trast compared to the standard T1-dependent imaging sequences we  
B 22 currently employ (400/15 2D spin echo and 30/5 3D FLASH). Due to  
23 the very short TE of the RAGE acquisition and the small voxel  
24 sizes, the images do not show any significant susceptibility ar-  
25 tifacts at air/soft tissue and bone/soft tissue interfaces. In  
I 26 Fig. 4c, note the bright appearance of the blood in the arteries  
B 27 surrounding the pituitary. During the 500ms delay period, fully  
28 magnetized blood flows into the transmit/receive head coil  
29 resulting in an inflow enhancement effect for the arteries.  
30 Blood that experiences the inversion pulse, such as that in the  
31 venous structures, appears dark in the images.  
32  
33  
34

EXAMPLE III

Figure 5 shows transverse T1-weighted head images (2mm thick) of a normal volunteer from a 3D set of 32 slices. The total acquisition time was 1.1 minutes. (preparation: 90° pulse followed by a 140ms delay; acquisition: FLASH sequence with TR/TE/Flip 12/5/15°, matrix 32x128x256, FOV 250mm, add sequential phase encoding; recovery: none)

EXAMPLE IV

Figure 6 shows transverse T2-weighted head images (2mm thick) of a normal volunteer from a 3D set of 32 slices. The total acquisition time was 4.3 minutes (preparation: driven equilibrium (90°-180°-90°) with an echo time of 56ms followed by a 42ms delay for spoiling; acquisition: FISP sequence with TR/TE/Flip 14/5/10°, matrix 32x128x256, FOV 250mm, centrally reordered phase encoding in the slice select direction; recovery: 1454ms).

GLOSSARY

2D: Two-dimensional.

3D: Three-dimensional.

3D MP RAGE: Three-Dimensional Magnetization-Prepared Rapid Gradient Echo. The MRI pulse sequence technique which is the subject of this invention.

CSF: Cerebrospinal fluid.

Contrast: The difference in signal intensity from two tissues, sometimes scaled to a reference intensity value.

P 1 Contrast-to-noise ratio: The difference in signal intensity from  
2 two tissues, scaled by a measure of the random noise signal in  
3 the image. The contrast-to-noise ratio provides an indication of  
4 how well the tissues can be distinguished from each other.  
5 CNR: Contrast-to-noise ratio.

A 6  
7 Excitation: In a general sense, the delivery of energy into the  
8 spin system using a radio-frequency pulse. An RF pulse whose  
9 purpose is to produce transverse magnetization that can later be  
10 measured is commonly referred to as an excitation pulse.

P  
B 11  
12 Echo-Planar: Disclosed in Mansfield P. Multi-Planar Image For-  
13 mation Using NMR Spin Echos, Journal Phys Chem 10, L55, 1977,  
14 Stehling MK, Ordidge RJ, Coxon R, et al, Ultra-High-Speed Inver-  
15 sion Recovery Echo Planar MR Imaging: Technique and Application,  
B 16 and Radiology 169(P), 377, 1988 (abstract), and Stehling MK, Or-  
17 didge RJ, Coxon R, Mansfield P. Inversion-Recovery Echo-Planar  
B 14 18 Imaging (IR-EPI) at 0.5T. Magn Reson Med 13, 514-517, 1990.

19  
20 FAST: Fourier Acquired Steady state. See fast imaging with  
21 steady precession. Gyngell ML. The Application of Steady-State  
22 Free Precession in Rapid 2DFT NMR Imaging: FAST and CE-FAST Se-  
B 14 23 quences. Magn Reson Imaging 6, 415-419, 1988.

24  
25 Fast imaging with steady precession: A short-TR partial flip  
26 angle gradient-echo pulse sequence that employs a steady-state of  
27 the complete magnetization vector. That is, the gradient struc-  
28 ture of the sequence is balanced such that a spin group at any  
29 given fixed physical position experiences the same precession  
30 angle history with each sequence repetition.



P 1 Fast low-angle shot: A short-TR partial flip angle gradient-echo  
2 pulse sequence that employs a steady-state of the longitudinal  
3 component of the magnetization vector. That is, the transverse  
4 magnetization introduced by a given excitation pulse (ideally)  
5 contributes only to the echo signal immediately following the  
6 pulse. Often, some type of spoiling is employed in this  
7 type of sequence to reduce or eliminate potential artifacts from  
8 residual transverse magnetization.

9  
10 FFE: Fast Field Echo. See fast low-angle shot.

B 11 van der Meulen P, Groen JP, Cuppen JJM. Very Fast MR Imaging by  
L 12 Field Echoes and Small Angle Excitation. Magn Reson Imaging 3,  
13 297-299, 1985.

P 14  
L 15 FISP: Fast Imaging with Steady Precession.

16  
P 17 FLASH: Fast Low-Angle Shot.

B 18 Haase A, Frahm J, Matthaei D, et al. FLASH Imaging. Rapid NMR Im-  
L 19 aging Using Low Flip-Angle Pulses. J Magn Reson 67, 258-266,  
20 1986.

P 21  
22 Flip angle: The angle of rotation of the magnetization vector  
23 produced by an RF pulse. The angle is measured with respect to  
24 the longitudinal axis, the direction parallel to the main mag-  
25 netic field.

P 26  
27 Gd-DTPA: A commonly used paramagnetic MRI contrast agent  
28 (chelated gadolinium) that is employed to reduce T1 relaxation  
29 times for increased lesion conspicuity.

P 30  
31 Gradient echo: A refocusing of phase coherence among spin  
32 isochromats at different positions along the magnetic field  
B 33 gradient resulting from (1) balanced negative and positive  
34

B 1 gradient pulses, or (2) balanced gradient pulses of the same sign  
2 on opposite sides of an RF pulse. A gradient echo does not  
3 refocus phase shifts due to static field inhomogeneities, suscep-  
4 tibility differences or chemical shift.

P 5  
6 Gradient pulse: A briefly applied magnetic field gradient.

P 7  
8 GRASS: Gradient Recalled Acquisition in Steady State. See fast  
9 imaging with steady precession. Utz JA, Herfkens RJ, Glover G,  
10 Pelc N. Three Second Clinical NMR Images Using a Gradient  
11 Recalled Acquisition in a Steady State Mode (GRASS). Magn Reson  
12 Imaging<sup>4</sup>, 106, 1986 (abstract).  
13

P 14 Hybrid: Haacke EM, Bearden FH, Clayton JR, Linga NR.  
15 Reduction of MR Imaging Time by the Hybrid Fast-Scan Technique.  
B14 16 Radiology 158, 521-529, 1986.  
17

P 18 Inversion: A non-equilibrium state in which the magnetization  
19 vector is anti-parallel to the direction of the main magnetic  
31 B 20 field (i.e. along the -z axis). An inversion pulse is a 180° RF  
21 pulse which rotates the longitudinal component of the magnetiza-  
31 22 tion vector from the +z axis to the -z axis.  
23

P 24 k-space volume: The magnetic resonance spatial frequency data set  
25 which defines the acquired image.  
26

P 27 Longitudinal component of the magnetization vector: The projec-  
28 tion of the magnetization vector onto an axis parallel to the  
29 direction of the main magnetic field. The longitudinal axis is  
30 generally referred to as the z-axis.  
31

P 32 Longitudinal magnetization: The longitudinal component of the  
33 magnetization vector.  
34

P 1 Longitudinal relaxation: The process by which the longitudinal  
2 component of the magnetization vector relaxes to its thermal  
3 equilibrium value aligned with the main magnetic field. The  
4 relaxation takes place with a characteristic time constant T1.

B 5 Low flip angle: A flip angle less than 90°.  
6

P 7 Magnetic field gradient: A magnetic field whose strength varies  
8 with position. Generally, linear gradients are used for MRI.  
9

P 10 Magnetization preparation (MP) period: In an MP RAGE sequence,  
11 the period preceding data acquisition in which a series of RF  
12 pulses, gradient pulses, and time delays are applied to encode  
13 the desired contrast properties in the form of longitudinal mag-  
14 netization. The term is employed herein to generically include  
15 pulse sequence techniques, such as snapshot FLASH imaging. When  
16 this preparation is applied to the object of interest, dif-  
17 ferences are developed in the amplitude and/or phase of the mag-  
18 netization vector based on the tissue properties. Since the  
19 prepared contrast is subsequently sampled by the rapid gradient-  
20 echo sequence, the tissue dependent differences in the magnetiza-  
21 tion vector must be generated as, or converted to, differences in  
22 the longitudinal component of the magnetization vector.  
23

P 24 Magnetization recovery period: In an MP RAGE sequence, the period  
25 following data acquisition which allows T1 and T2 relaxation  
26 before the start of the next sequence cycle.  
27

P 28 Magnetization vector: The net magnetic moment resulting from a  
29 group of spins.  
30  
31  
32  
33  
34

P 1 Matrix size: Specifies the number of data points along each  
2 dimension in the digital image or volume image set. For example,  
B33-3 a 2D image might be specified as 128x256, and a 3D image set  
L33H4 might be specified as 128x128x128, or equivalently  $128^3$ .

P 5  
6 Motion artifacts: A misregistration of signal from tissues which  
7 move during the acquisition of the image data. Common sources of  
8 motion artifacts include respiratory motion, cardiac motion,  
9 blood flow, eye movement, swallowing, and voluntary motion.

P 10  
11 MP RAGE: Magnetization Prepared Rapid Gradient Echo.

12  
13 MRI: Magnetic Resonance Imaging.

14  
15 ms: milliseconds.

L B 16  
17 Multi-slice: Refers to 2D imaging techniques which acquire more  
18 than one image slice at a time, usually by interleaving (in time)  
19 several slice acquisitions within TR.

P B 20  
21 Partial flip angle: A flip angle less than  $90^\circ$ .

P 22  
23 Phase-encoding: The process of encoding the spatial position by  
24 applying a position dependent phase shift to the spin system  
25 before signal acquisition. The phase shift is incremented  
26 linearly with each sequence repetition.

P 27  
28 Point spread function: The inverse Fourier transform of the fil-  
29 ter function in the spatial frequency domain.

P 30  
31 Proton density: The quantity of signal producing protons in a  
32 given volume divided by the volume.

P  
L  
1 PSF: Point Spread Function.

2  
3 Pulse sequence: A combination of RF pulses, gradient pulses, and  
4 time delays designed to produce images with specific contrast  
5 properties.

P  
6 RAGE: A generic acronym for rapid gradient echo, and referring  
7 to an acquisition period which is relatively short compared to  
8 the T1 values of interest.

P  
9  
10 Rapid acquisition with relaxation enhancement: A rapid imaging  
11 technique that employs repeated spin echoes with different  
12 phase-encodings to collect a complete image with only one or a  
13 few excitation pulses.

P  
14  
15 RARE: Rapid Acquisition with Relaxation Enhancement.

16 Hennig J, Nauerth A, Friedburg H. RARE Imaging: A Fast Imaging  
17 Method for Clinical MR.

B14  
18 Magn Reson Med 3, 823-833, 1986.

P  
19  
20 RF: radio frequency.

L  
21  
22 RF pulse: A brief application of RF energy.

23  
24 Signal-to-noise ratio: The ratio of the signal intensity from a  
25 tissue to a measure of the random noise level in the image.

P  
26  
27 Slice profile: The spatial distribution of the relative signal  
28 contributions to a given image intensity value measured along the  
29 direction perpendicular to the plane of the slice.

P  
30  
31 SNR: Signal-to-Noise Ratio.

P 1 Snapshot FLASH imaging: Haase et al (Haase A, Matthaei D,  
2 Bartkowski R, et al. Inversion Recovery Snapshot FLASH MR Imag-  
B14 3 ing. J Comput Assist Tomogr 13, 1036-1040, 1989. Haase A.  
4 Snapshot FLASH MRI. Applications to T1, T2, and Chemical-Shift  
B17 5 Imaging. Magn Reson Med 13, 77-89, 1990.  
6

P 7 Spatial frequency space: Physical coordinate space (the spatial  
8 domain) and spatial frequency space (the spatial frequency  
9 domain) are related via the Fourier transform. Since the MR im-  
10 aging process physically performs a Fourier transform on the spin  
11 system, the signal that is measured during the MRI experiment  
12 represents the spatial frequency components corresponding to the  
13 desired image.  
14

P 15 Spin echo: A refocusing of phase coherence among spin  
16 isochromats resulting from the application of two RF pulses. The  
17 echo occurs such that the time between the two RF pulses equals  
18 the time between the second RF pulse and the echo. A spin echo  
19 refocuses phase shifts due to static field inhomogeneities, sus-  
20 ceptibility differences, and chemical shift.  
21

P 22 Spin isochromat: A macroscopically small group of spins that all  
23 experience the same magnetic field strength.  
24

P 25 Spoiling: The application of additional gradient pulses or RF  
26 phase shifts in an attempt to destroy the phase coherence of the  
27 transverse magnetization before the succeeding excitation pulse.  
28

P 29 Steady state: Sequences which are based on either a steady state  
30 of the longitudinal component of the magnetization (e.g., stan-  
31 dard spin-echo or FLASH) or a steady state of the complete mag-  
32 netization vector (e.g., FISP or GRASS).  
33  
34

P 1 T1: The spin-lattice or longitudinal relaxation time. See lon-  
2 gitudinal relaxation.

P 3  
4 T1-weighted: Refers to image contrast which displays a rela-  
5 tively strong dependence on the tissue T1 values.

Q 6  
7 T2: The spin-spin or transverse relaxation time. See transverse  
8 relaxation.

P 9  
10 T2-weighted: Refers to image contrast which displays a rela-  
11 tively strong dependence on the tissue T2 values.

P 12  
13 Temporal event: An event such as a patient's respiration or  
14 heart beat.

P 15  
16 TE: Echo time for the pulse sequence.

L 17  
18 TR: Repetition time for the pulse sequence.

19  
20 Transverse component of the magnetization vector: The projection  
21 of the magnetization vector onto a plane perpendicular to the  
22 direction of the main magnetic field. The transverse plane con-  
23 tains the x and y axes.

P 24  
25 Transverse magnetization: The transverse component of the mag-  
26 netization vector.

P 27  
28 Transverse relaxation: The process by which the transverse com-  
29 ponent of the magnetization vector relaxes to its thermal equi-  
30 librium value of zero. The relaxation takes place with a charac-  
31 teristic time constant T2.

P 1 Truncation artifacts: Image artifacts which are sometimes ap-  
2 parent at rapid transitions in signal intensity. These artifacts  
3 appear when the image acquisition does not acquire a sufficient  
4 range of spatial frequency values to adequately describe the  
5 given spatial distribution of intensities.

P 6  
7 Voxel: Volume element. The volume which corresponds to a given  
8 discrete intensity value in the image.